

# 4S Fugro Drone

# Technical information and first result Wismar Bay test

Manfred Stender; EOMAP SDB Day; 40.10.2022



Our business and motivation for drone operation

Fugro 4S drone and their payload

First results from test flight "Wismar Bay" (Baltic Sea)

UGRO

Into the future

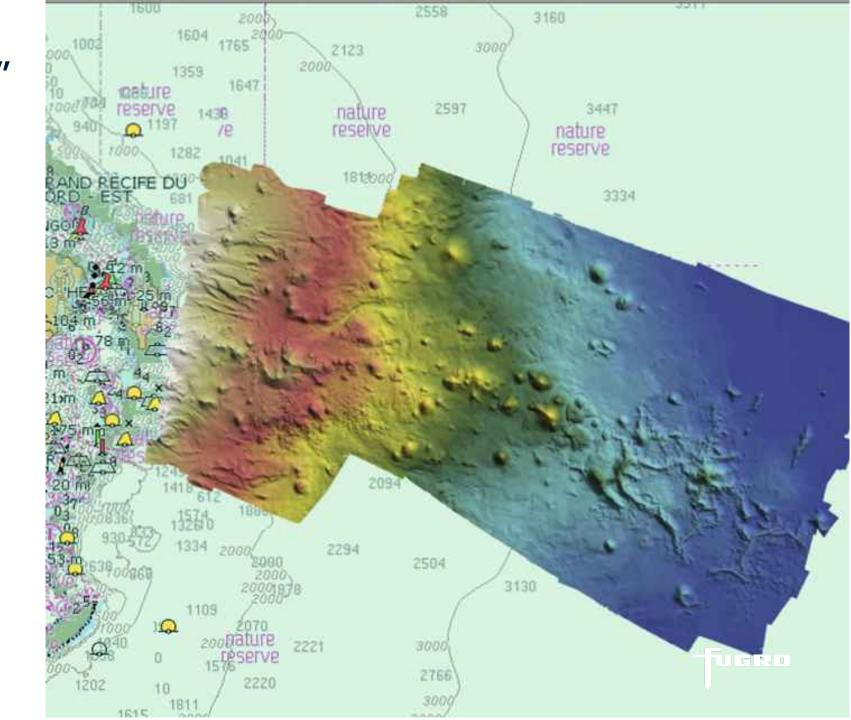


"Excellent Cluster" Hydrography & (telecom) Cable Route Survey

worldwide

**IFREMER MAYOBS13-2** 

Courtesy of IFREMER



FUGRO Dashboard Cable Route Surveys approx. 2020 to 2022 Nm

1

3000 km

# From BMH to **Deeper Waters**

clients requirements, our tools

Bathymetry / Topographie Surface Geology Sub-surface Geology **Object Detection** 

250m Low Water Safe Operating Limit \* 250m 20m Contour 50m Contour 100m Contour .......... 250m







......

250m

250m

3500

325m

250m

.........

Overlap

0

50m C

100m

250r

BMH



**fugro** 



# Landing site surprises

Vacation feeling or high-risk experiences with security guards

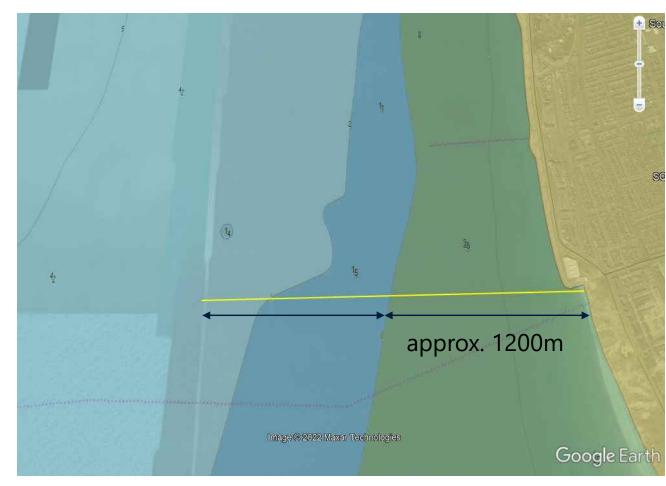






# Long distances to walk

Time constrains due to tidal regime







# Data derived from satellite images

DTM determination and SDB to fill gaps

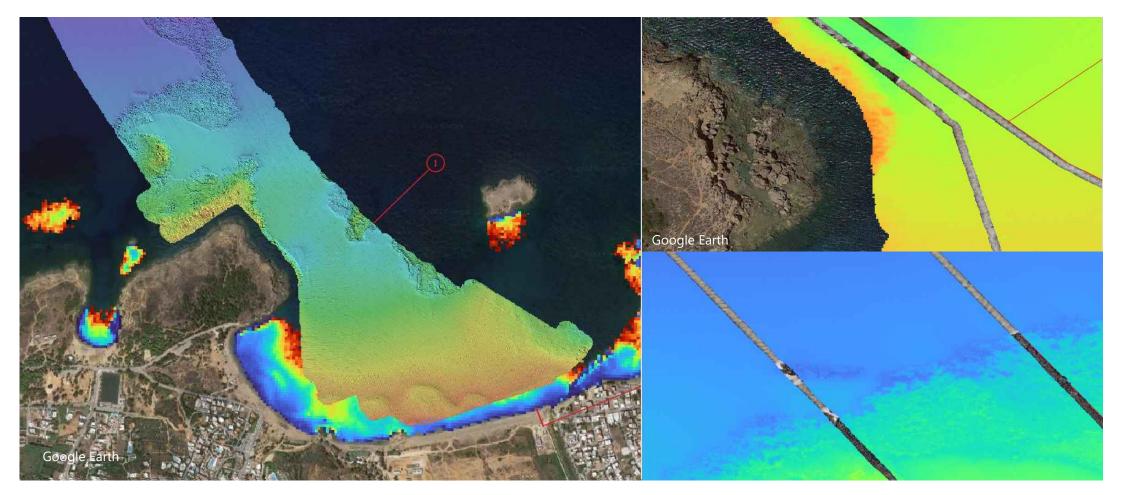
SDB to fill shallow water gaps DTM determination based on commercial SAT image (resolution 0.5m)



**F**UGRO

# **Satellite Derived Bathymetry**

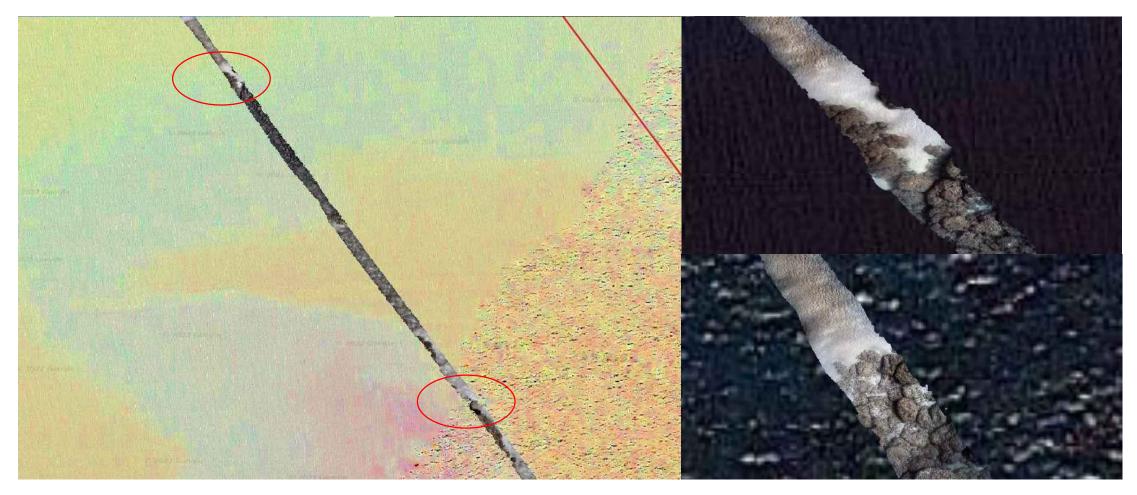
Still some gaps open and information missing





# **Crosscheck with SAT images**

No SDB, but still valuable information in SAT images



# Multi Sensor Results

Dealing with Resolutions

MBES (15m flight height)

- Grid resolution >20cm
  SSS (15m flight height)
- Grid resolution > 10cm
  Video (3m flight height)
- Pixel size > > 1cm
  SDB (free images)
- Sentinel-2 10m (!)
  SDB (commercial images)
- WorldView2 2m (!) SDB (drone)
- expected 5-10 cm



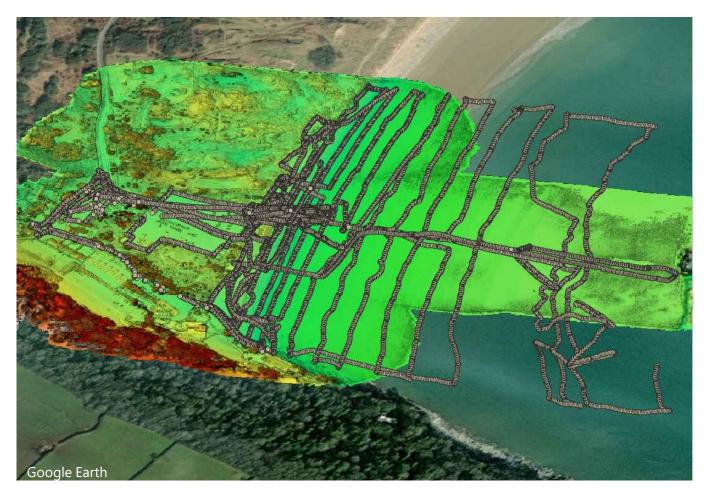




# Already: Photogrammetry by Drone

From onshore extended to nearshore by multispectral

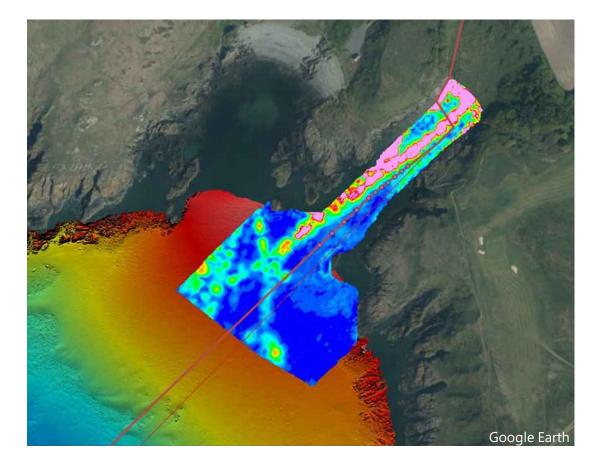


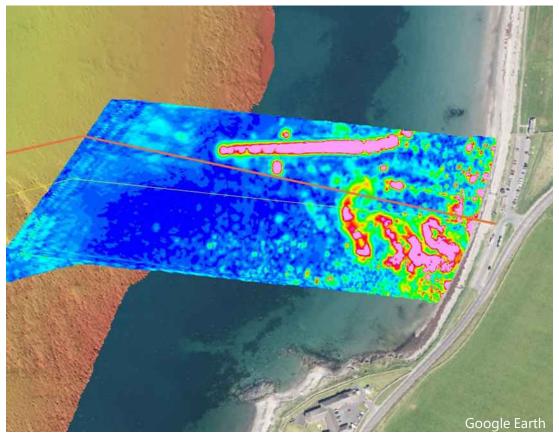




# Already: Magnetometer Survey by Drone

Another application suitable for drones at beach and nearshore







# Fugro 4S Drohne

Combined topographic and bathymetric / benthic survey platform



DJI 1000S



2 GNSS Receivers



DSLR (RGB) camera



Multispectral camera

14 EOMAP SDB Days; 04.10.2022



# Drone and sensor payload

technical information

Drone modell DJI 1000S include DJI flight controller

Sensor suite:

2 antenna GNSS positioning and heading system

MAIA multispectral camera for SDB or environmental survey

SONY 5000 DSLR camera for photogrammetric top / shallow water survey

Total TOW: approx. 11kg

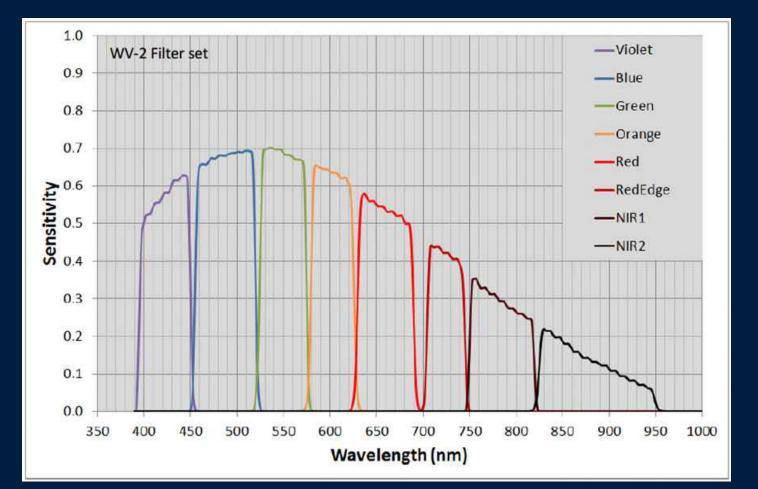


# EOPTIS SRL "MAIA"

Sensitivity of the MAIA MS camera optical band with World View 2 filter set

The imaging sensors features 1.2Mpix resolution, highsensitivity and global shutter technology, allowing the simultaneous acquisition of images free from motion artifacts at a frame rate up to 5Hz.

Interfaced to an *external GPS* to trigger the <u>acquisition start</u> and to get the <u>position of the camera</u> at the time of shot. The geo-tagged images are thus stored in an **internal solid state non-volatile memory**.



IGRO

# **GNSS** positioning bar

Precisse heading and positioning by two antenna, GNSS raw data recording and postprocessing

H-MSL	Easting	Northing	SDHoriz	SDHeight
(m)	(m)	(m)	(m)	(m)
83.076	653338.286	5981398.264	0.165	0.203
83.074	653334.304	5981403.211	0.164	0.200
82.988	653330.355	5981408.226	0.164	0.200
82.950	653326.360	5981413.254	0.164	0.199
82.946	653322.291	5981418.306	0.164	0.199
82.993	653318.210	5981423.349	0.164	0.199
82.986	653314.131	5981428.529	0.164	0.199
83.049	653310.053	5981433.720	0.164	0.199
83.100	653305.937	5981438.912	0.164	0.199
83.107	653301.867	5981444.182	0.164	0.199
83.119	653297.783	5981449.456	0.164	0.199
82.985	653293.688	5981454.702	0.164	0.199
82.964	653289.524	5981459.970	0.164	0.199
83.043	653285.356	5981465.266	0.164	0.199
82,992	653281.173	5981470.534	0.164	0.199
83,065	653276.997	5981475.827	0.164	0.199
83.056	653273.141	5981480.556	0.164	0.199
83.030	653269.554	5981484.924	0.164	0.199
82,976	653266.032	5981489.361	0.164	0.199
83.067	653262.521	5981493.831	0.164	0.199
83.033	653259.122	5981498.238	0.164	0.199
83.041	653255.704	5981502.602	0.164	0.200
83.088	653252.273	5981507.020	0.165	0.202
83.298	653249.192	5981509.817	0.165	0.202
83.398	653248.946	5981508.008	0.166	0.205
84.041	653251.729	5981503.796	0.166	0.205
83,966	653254.997	5981499.785	0.166	0.205
83.351	653258.334	5981495.515	0.166	0.206
83.031	653261.976	5981490.657	0.166	0.206
82.533	653265.711	5981485.836	0.166	0.207
81.849	653277.310	5981471.310	0.166	0.208
81.808	653281.192	5981466.541	0.166	0.206
81.879	653284.980	5981461.711	0.166	0.206





# Test flight area Wismar Bay

Baltic Sea





# Test flight track plan

All lines with DSLR and multi spectral camera @80m flight height

All lines with DSLR and multi spectral camera @70m flight height

Two flights @ approx. 12min each

Total about 5,5km of lines and >1200 images each camera system

Flown week 34/22, data evaluation still in progress, e.g. MS camera under the EU 4S project scope

**fugro** 

**Golfclub Hohen** 

Google Earth

# **Drone mobilisation**

Unpacking, sensor installation and preparation, last check,









# Drone ready for tack-off

Ground control and communication check, security at site

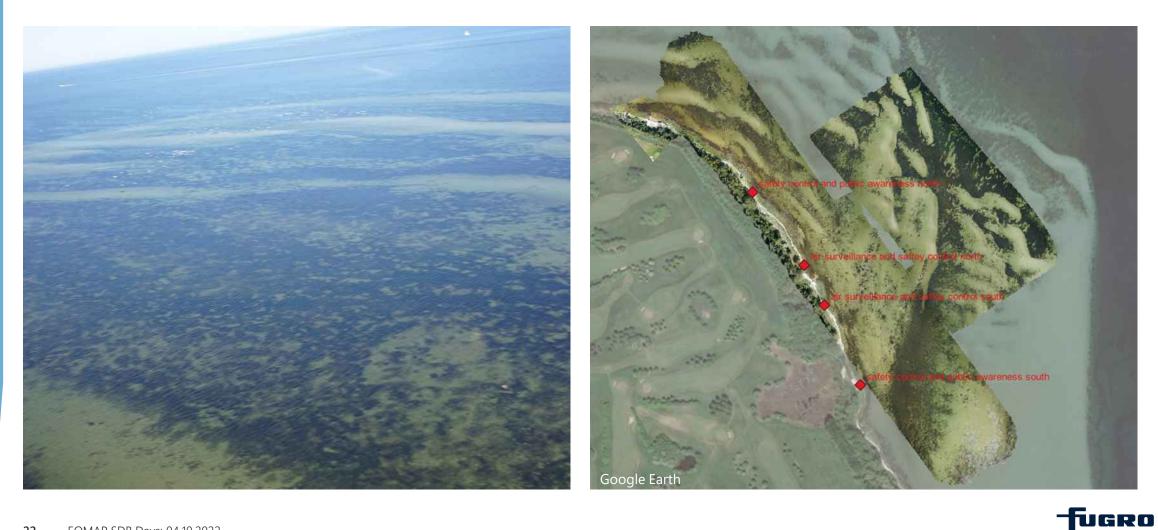






# Intermediate results and findings

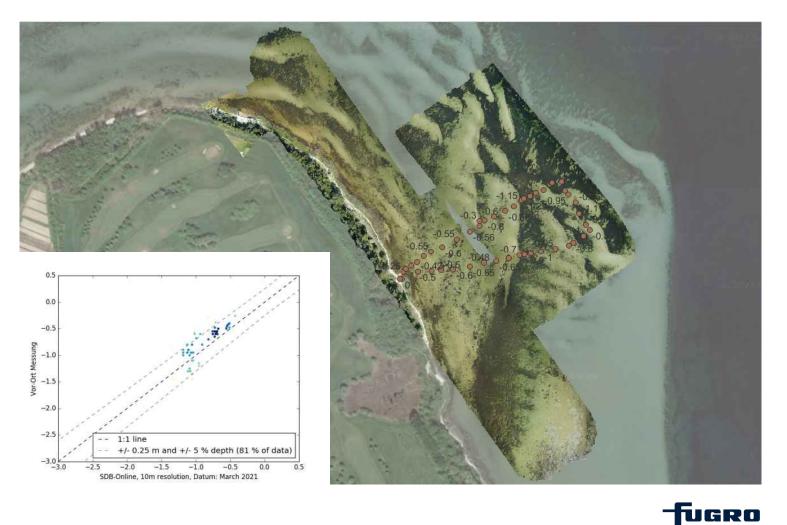
Orthomosaic created out of approx. 1200 RGB images



# **Control Point Survey**

Handheld Hydrography, comparison with SDB (Sentinel-2)

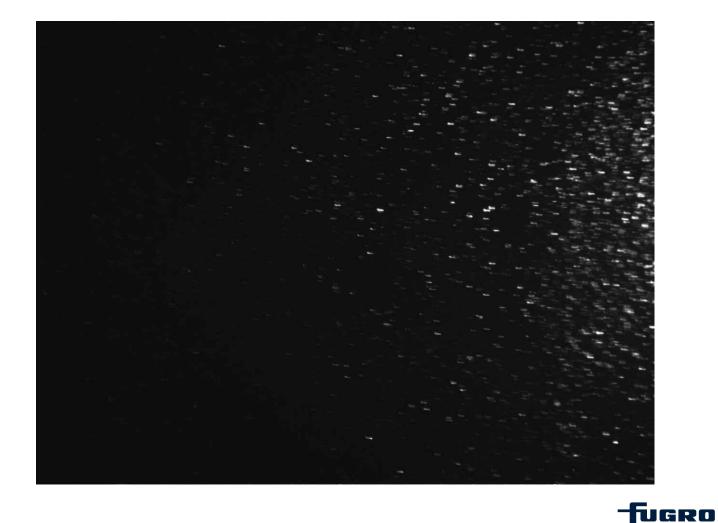




# **Misalignment of MAIA bands**

Correction need to improve resolution





## **SDB WITHOUT "S"** DRONE BASED BATHYMETRY

#### **Challenge 1: Method**

Inversion of the Radiative Transfer Equation (RTE) for MAIA 8-band drone sensor.

Spectral databases were created to allow for reflectance inputs of 80m flight records, matching the spectral response functions and respecting different recording geometries of the MAIA sensor.

Seafloor bottom albedo was defined by the drone records.

No on-site information were collected or used to run the RTE inversion process.



EOMV5

## **SDB WITHOUT "S"** DRONE BASED BATHYMETRY

#### Challenge 2: Big data

Massive amounts of multispectral, high bit depth, extremely high res data are collected by the drone records.

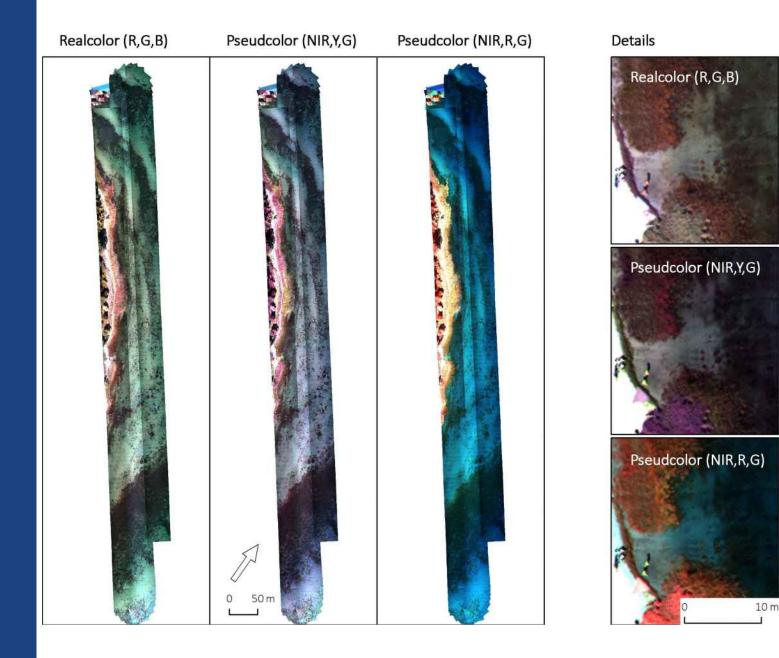
Parallelizing, cloud computation and ML methods have been applied to improve speed performance of the workflow. This in an ongoing activity.



#### DRONE MULTISPECTRAL RECORD

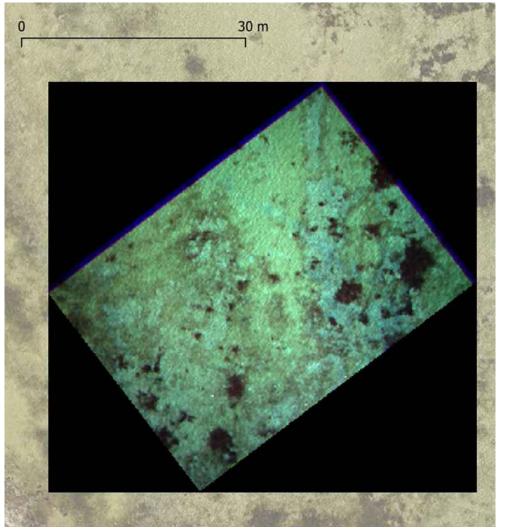
## WISMAR, GERMANY

- 8 band multispectral (blue to NIR)
- Spatial resolution of 3 cm
- Approx. 1500 single tiles
- Records in Aug 2021, coastal shallow waters of the German Baltic, near Wismar

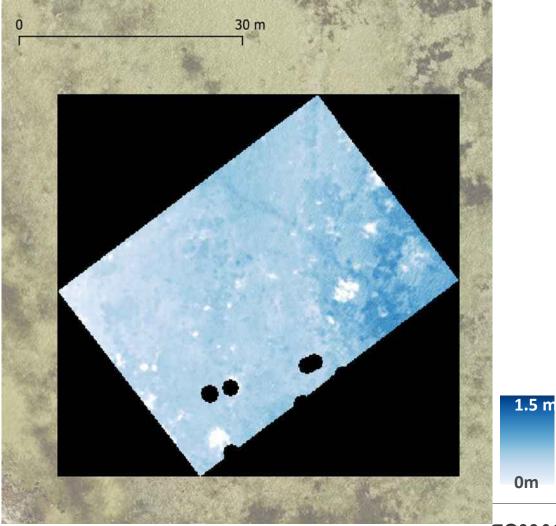


## **DRONE-DERIVED BATHYMETRY – FIRST RESULTS**

#### SINGLE MULTISPECTRAL IMAGE

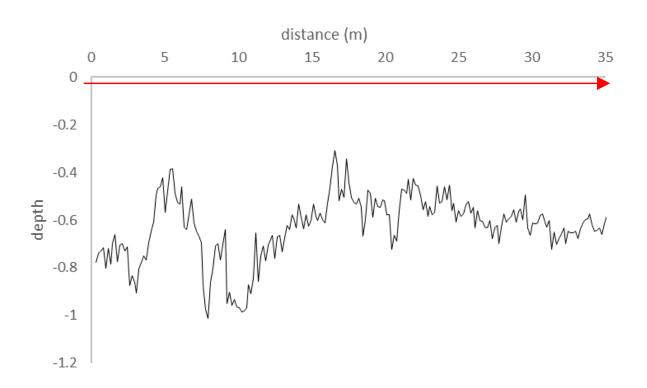


#### BATHYMETRY

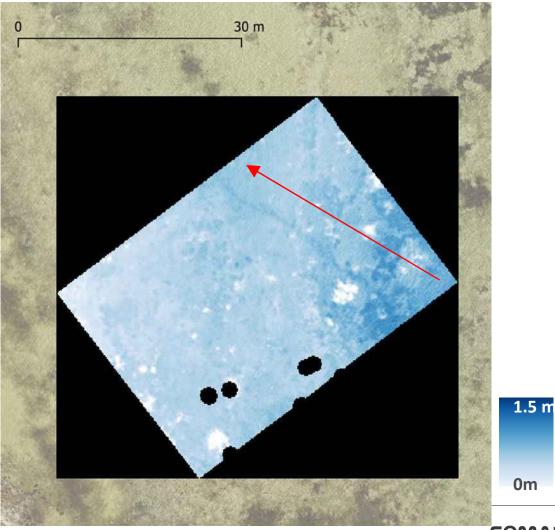


## **DRONE-DERIVED BATHYMETRY – FIRST RESULTS**

## SINGLE MULTISPECTRAL IMAGE



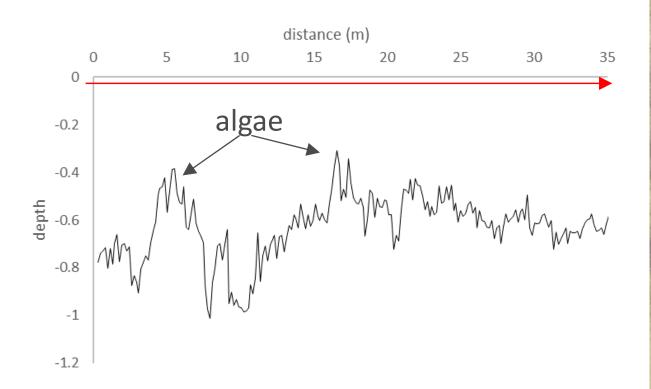
#### BATHYMETRY



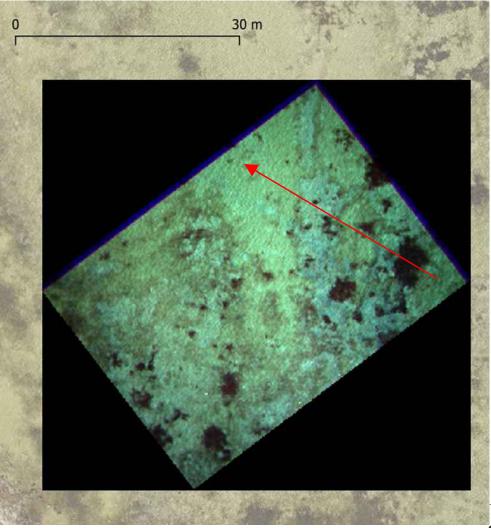
ΈΟΜΛΡ

## **DRONE-DERIVED BATHYMETRY – FIRST RESULTS**

## SINGLE MULTISPECTRAL IMAGE



#### BATHYMETRY



#### DRONE-DERIVED BATHYMETRY

## PRELIMINARY RESULTS

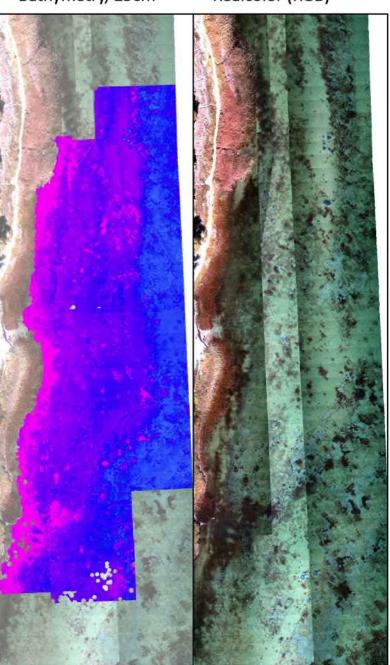
- Based on RTE inversion
- Bathymetry surface of 15 cm (3cm native resolution is possible)
- The very high resolution results in new challenges: geo-positioning, spectral band-matching, minimizing water surface effects, shadow effects

Bathymetry, 15cm

1.5 m

0m

Realcolor (RGB)



ΕΟΜΛΡ



## DRONE (MAIA SENSOR), 0.15M RESOLUTION



## **DRONE DERIVED BATHYMETRY, 15CM**

0

10 m

## **NEXT STEP** DRONE BASED BATHYMETRY

- 1. Increasing processing speed
- 2. Refining geopositioning
- 3. Testing on multiple sites and across different scenario
- 4. Enabling integration of on-site measurements
- 5. ....





# Into the future

Improvement of positioning and/or sensor alignment

Development of a solid workflow for "DDB" Introduction of "DDB" service to client Development of other product (envi) workflow Introduction of environmental survey capability to client

UGRO

Investigate fuel cell for longer flight time Development of a flying Subbottom Profiler

# Unlocking Insights from Geo-data