

New insights into aquatic systems with hyperspectral data: The EnMAP satellite and its water-related ground segment processors

Nicole Pinnel
and the entire EnMAP Team

Earth Observation Center (EOC)
Deutsches Zentrum für Luft- und Raumfahrt (DLR)



WATER DAYS

SDB Day &
EO Technology
Conference

4 – 6 October, 2022

Overview

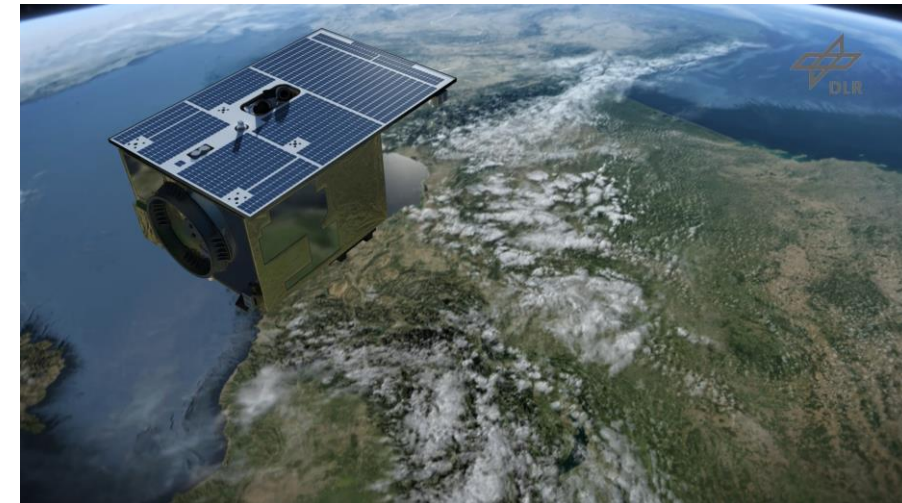
- EnMAP mission and participants, contributions from DLR
- EnMAP Technical Specifications
- Reception, processing and distribution
- EnMAP water-related ground segment processors
- Aquatic application examples



EnMAP Mission

EnMAP \equiv Environmental Mapping and Analysis Program

- Germany's first imaging-spectroscopy satellite-based earth observation mission
- Scientific Pathfinder mission for later operational services (CHIME, SBG)
- Regular provision of high-quality calibrated image products (orthorectification and atmospheric corrections)
- Observation of a wide range of ecosystem parameters,
e.g. Soils, minerals, land degradation
vegetation type and condition water quality



EnMAP Mission Consortium

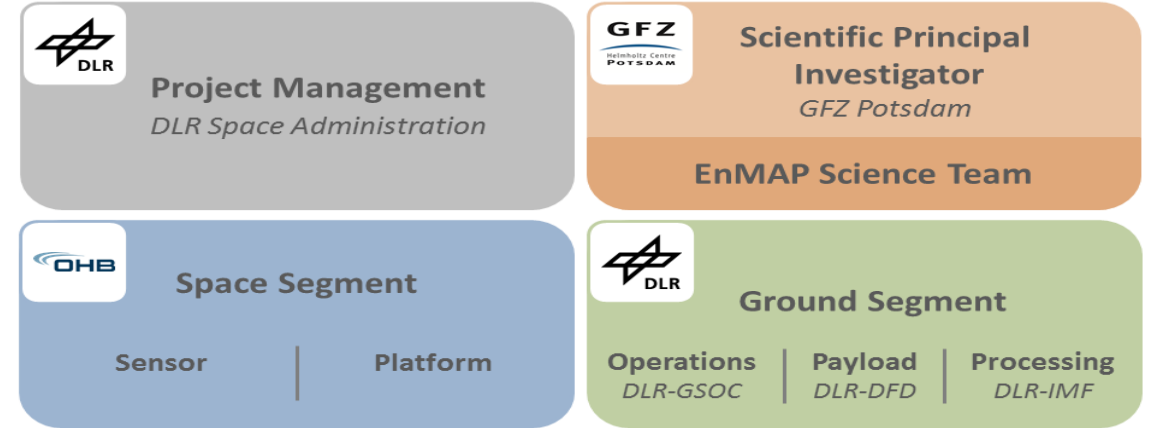


Supported by:



Federal Ministry
for Economic Affairs
and Climate Action

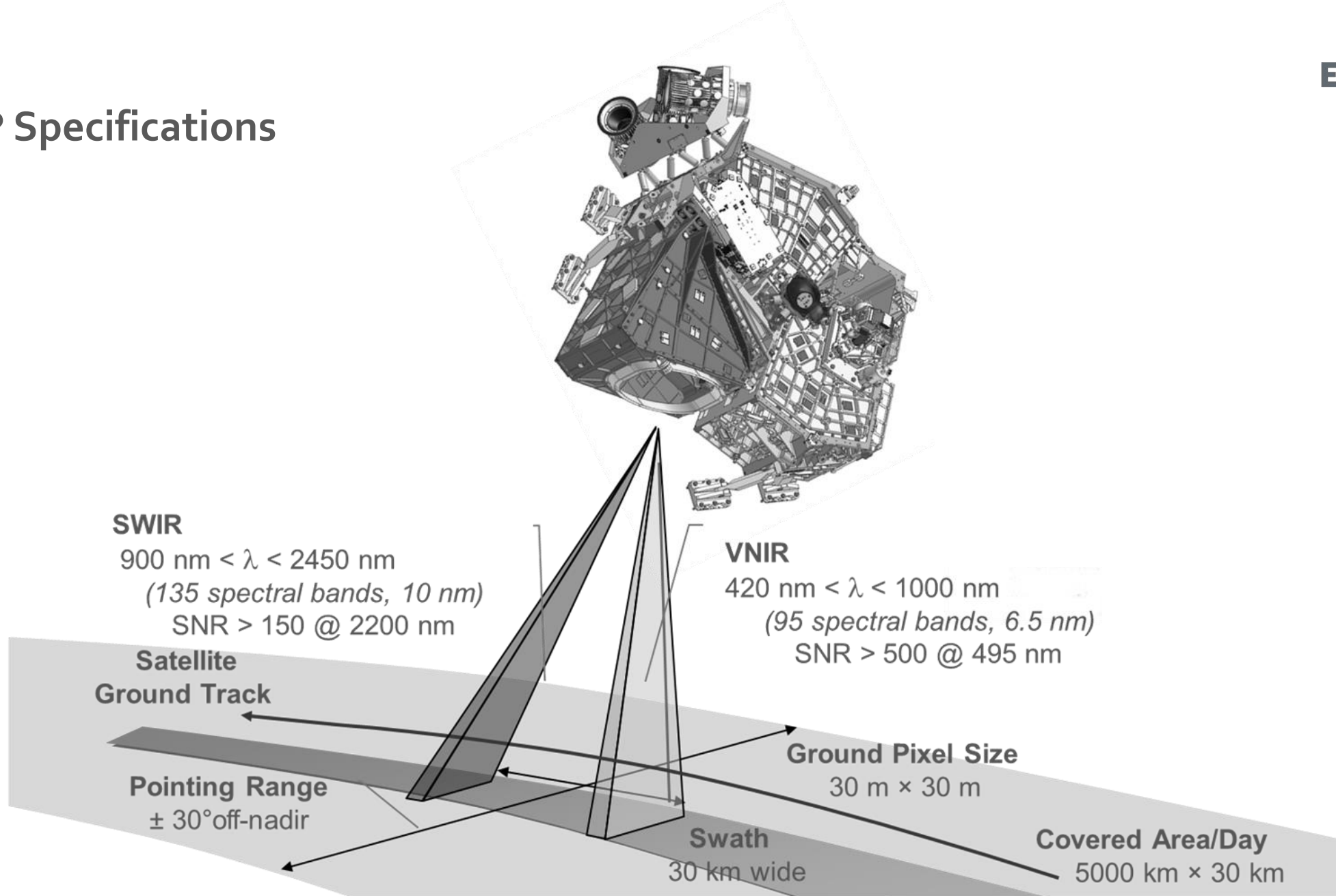
on the basis of a decision
by the German Bundestag



- The DLR Space Administration in Bonn is responsible for the overall project management
- The ground segment is formed by the EOC and the GSOC in Oberpfaffenhofen
- Core funding is provided by the Federal Ministry of Economics and Climate Policy
- In addition: Extensive Scientific Exploitation preparation program

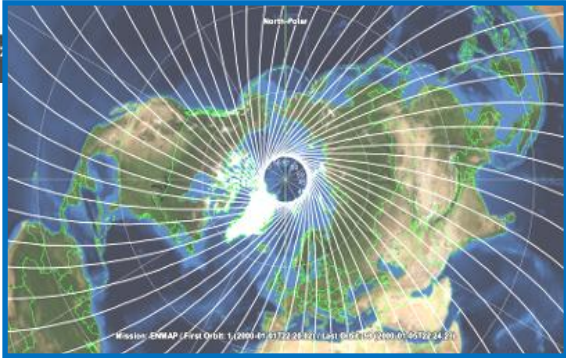
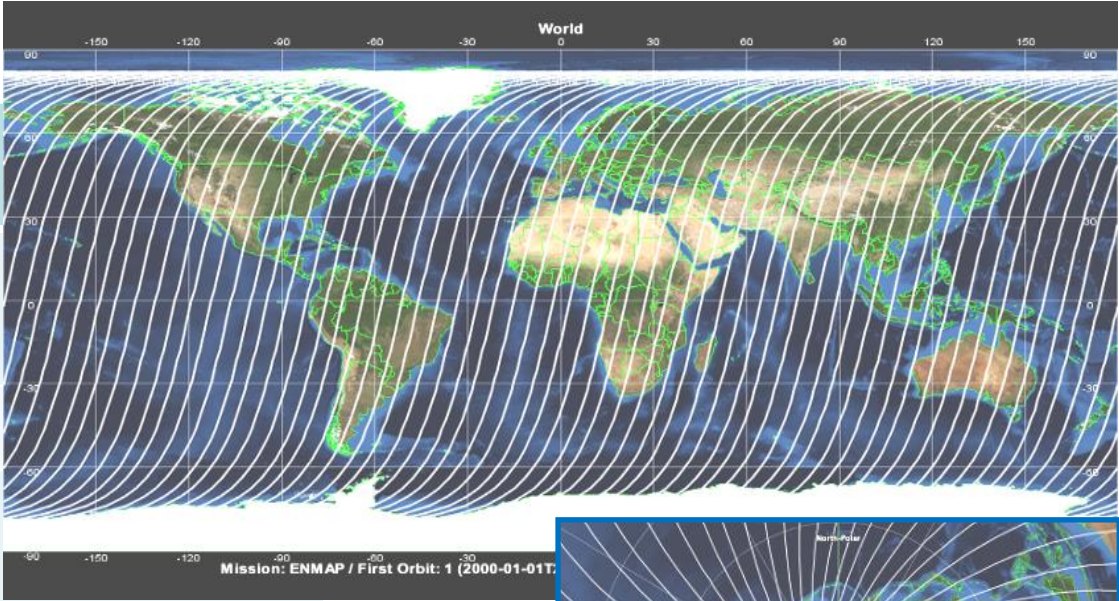


EnMAP Specifications

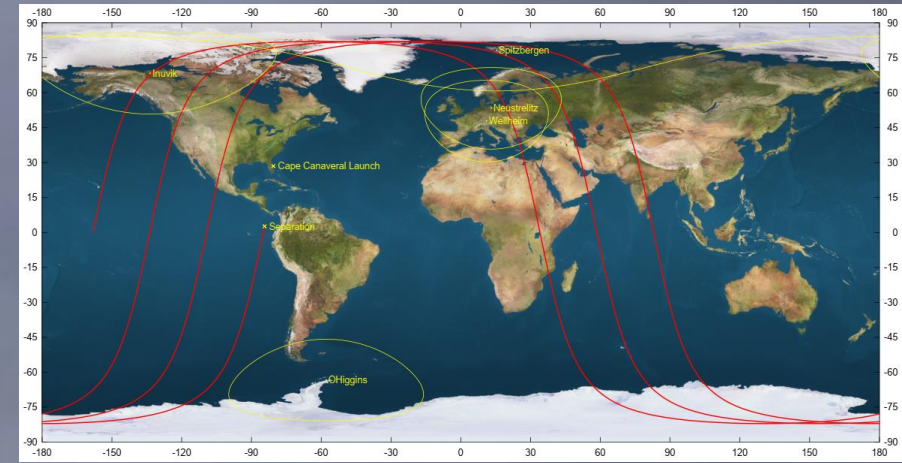


EnMAP Specifications

Parameter	Value
Target Lifetime	04/2022-04/2027 (currently in production phase)
Satellite (Mass, Dimension)	1000 kg, 3.1 m × 2.0 m × 1.7 m
Orbit (Type, Local Time at Equator, Inclination, Altitude, Repeat Cycle)	Sun-synchronous, 11:00, 98.0°, 653 km, 398 orbits in 27 days
Coverage	74° N to 74° S
Revisit	≤ 4 days (-30° to +30° across-track tilt) ≤ 27 days (-5° to +5° across-track tilt)



1st of April 2022



© SpaceX

LIFTOFF

STARTUP

MAX-Q

T+ 00:00:08

TRANSPORTER 4

SPEED

73

KM/H

ALTITUDE

0.0

KM

STAGE 1 TELEMETRY

© SpaceX

EnMAP Operation Phases

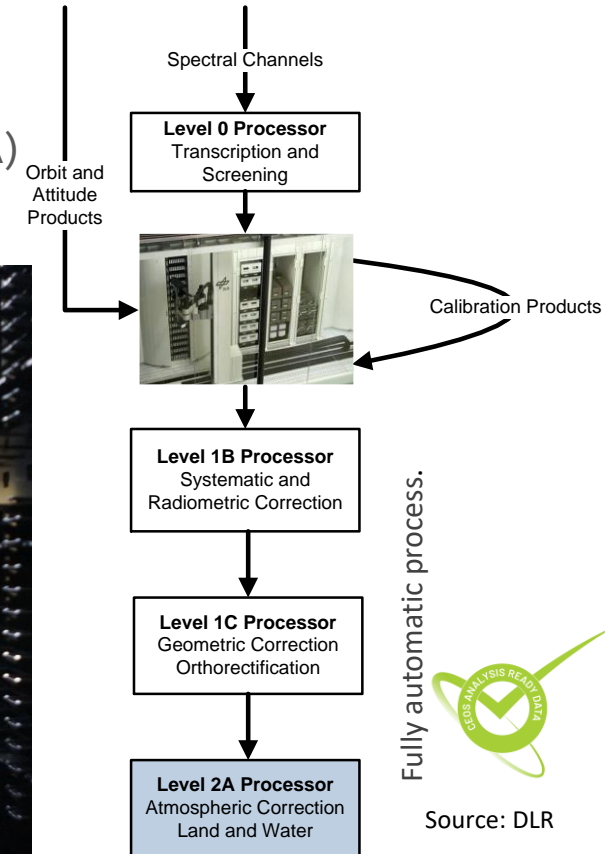
- Launch and Early Orbit Phase(14.04.2022, 2w)
- Commissioning Phase (6 m)
- Routine Phase (5 y)
- De-Commissioning Phase (3 m)



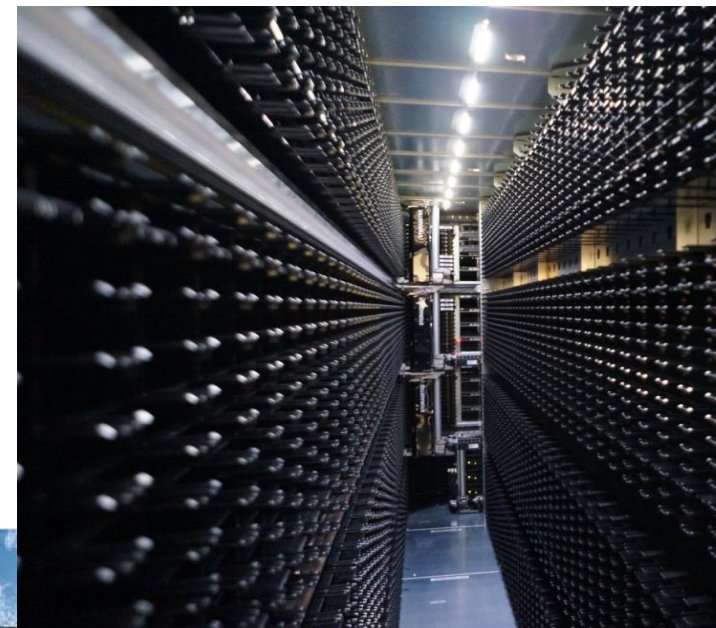
DFD-Station (Data receiving station),
Neustrelitz

GSOC-Station
(TMTC),
Weilheim

German Satellite
Data Archive (D-SDA)
und Web-Interfaces



Ground Control Center
(GSOC),Oberpfaffenhofen



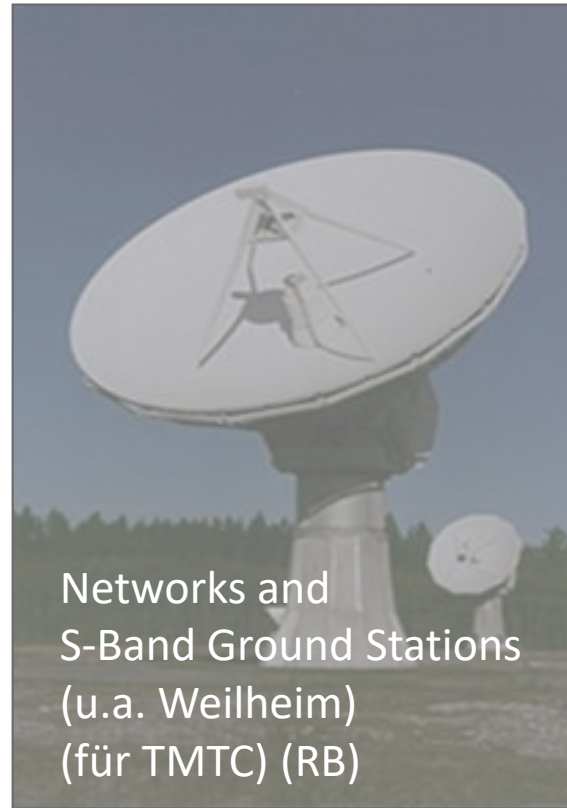
EnMAP Operation Phases

- Launch and Early Orbit Phase(14.04.2022, 2w)
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Ground Control Center
(GSOC),Oberpfaffenhofen



- Flight operations with planning and execution of mission operations as well as control and command (platform and instrument) (RB)
- Provision of position and location products Planning and execution of orbit maneuvers (RB)
- Mission planning using Reactive Planning (RB)



Networks and
S-Band Ground Stations
(u.a. Weilheim)
(für TMTC) (RB)

DFD-Station (Data
recieving station),
Neustrelitz

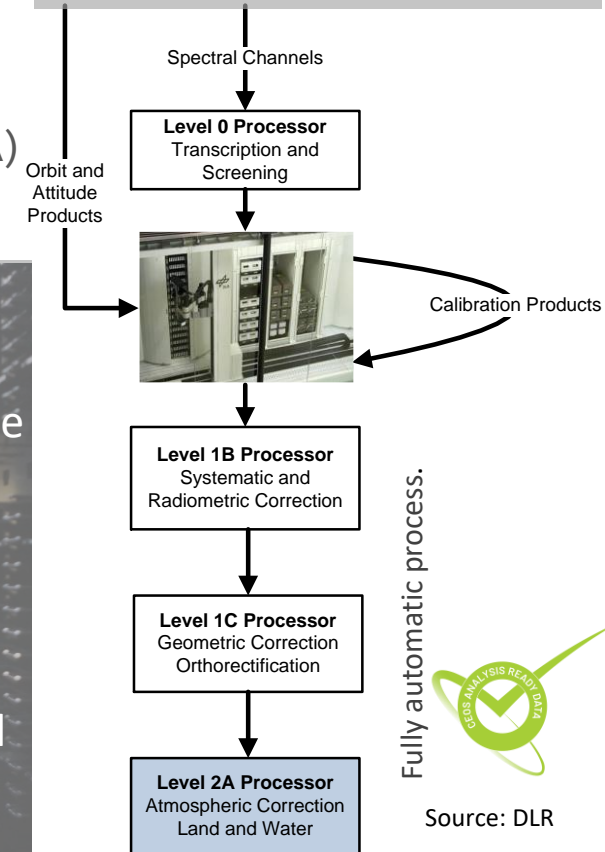
GSOC-Station
(TMTC),
Weilheim

German Satellite
Data Archive (D-SDA)
und Web-Interfaces

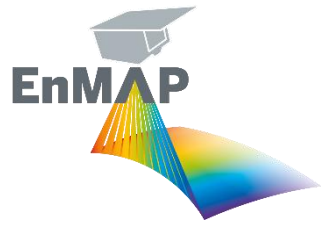


Networks and
X-Band Ground Station
(Neustrelitz & Inuvik)
(for data) (DFD)

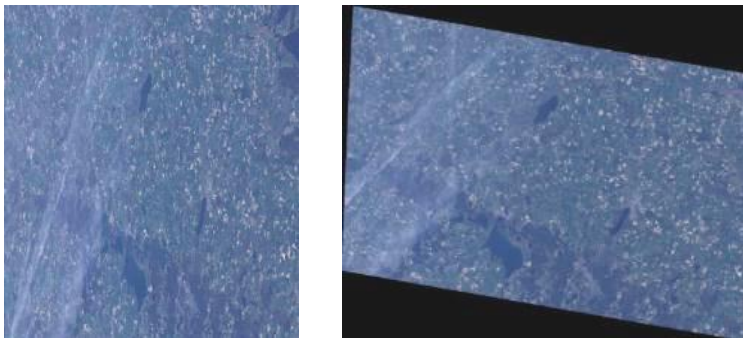
- Data processing for standard products (DFD)
- Instrument Calibration in Service (MF)
- Quality control of standard products (DFD/MF)
- Long-term archiving (DFD)
- User Interfaces (DFD) for record orders and product access



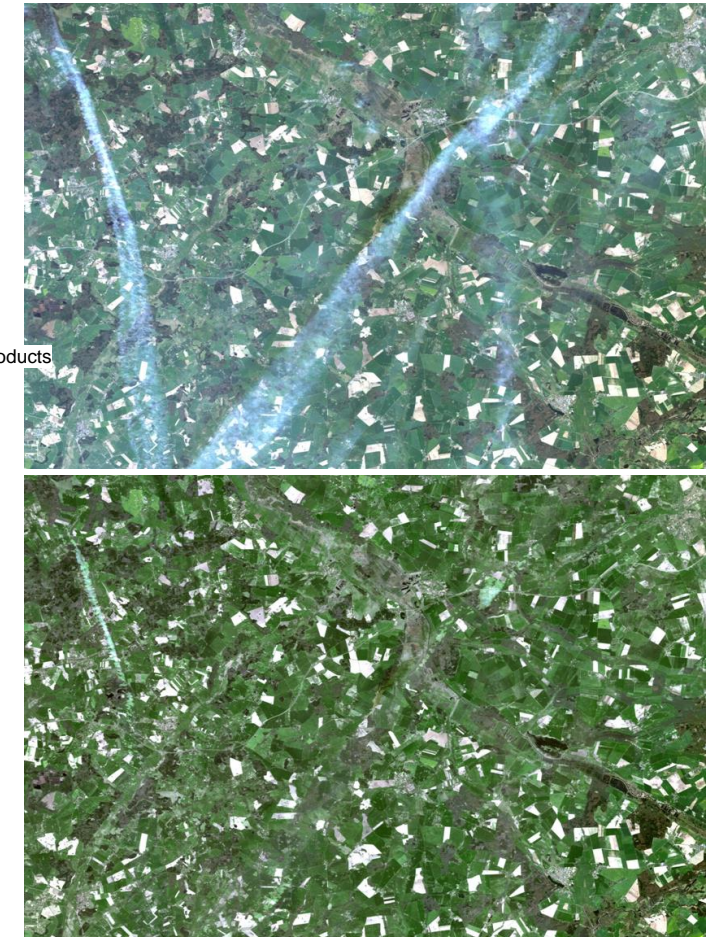
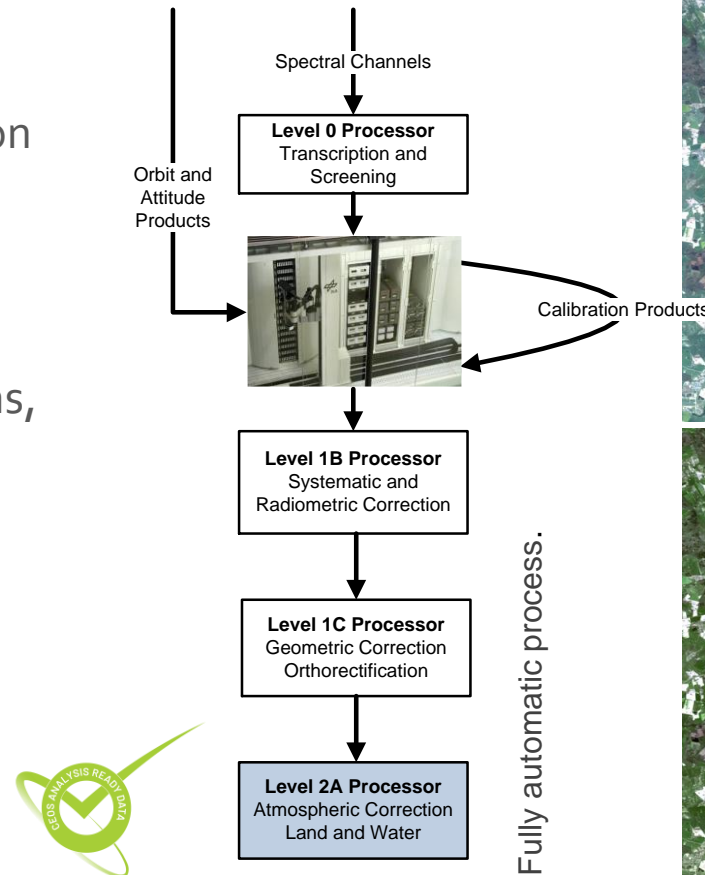
EnMAP Processor, Cal & QC System



- Development of a processing chain for
 - the systematic und radiometric correction (Level 1B)
 - orthorectification (Level 1C)
 - atmospheric correction (Level 2A)
- Calibration of the instrument during operations,
- Quality control of the products.

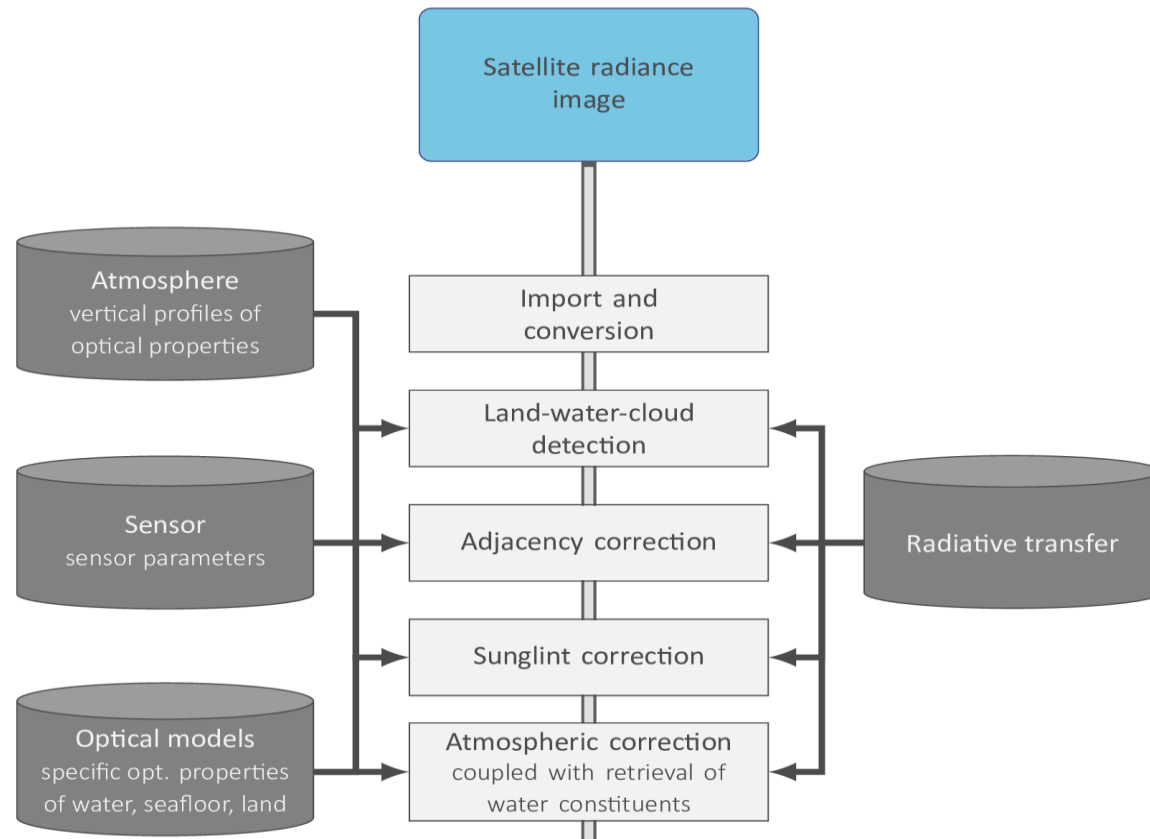


Orthorectification



Atmospheric Correction

EnMAP Water-related Ground Segment Processors

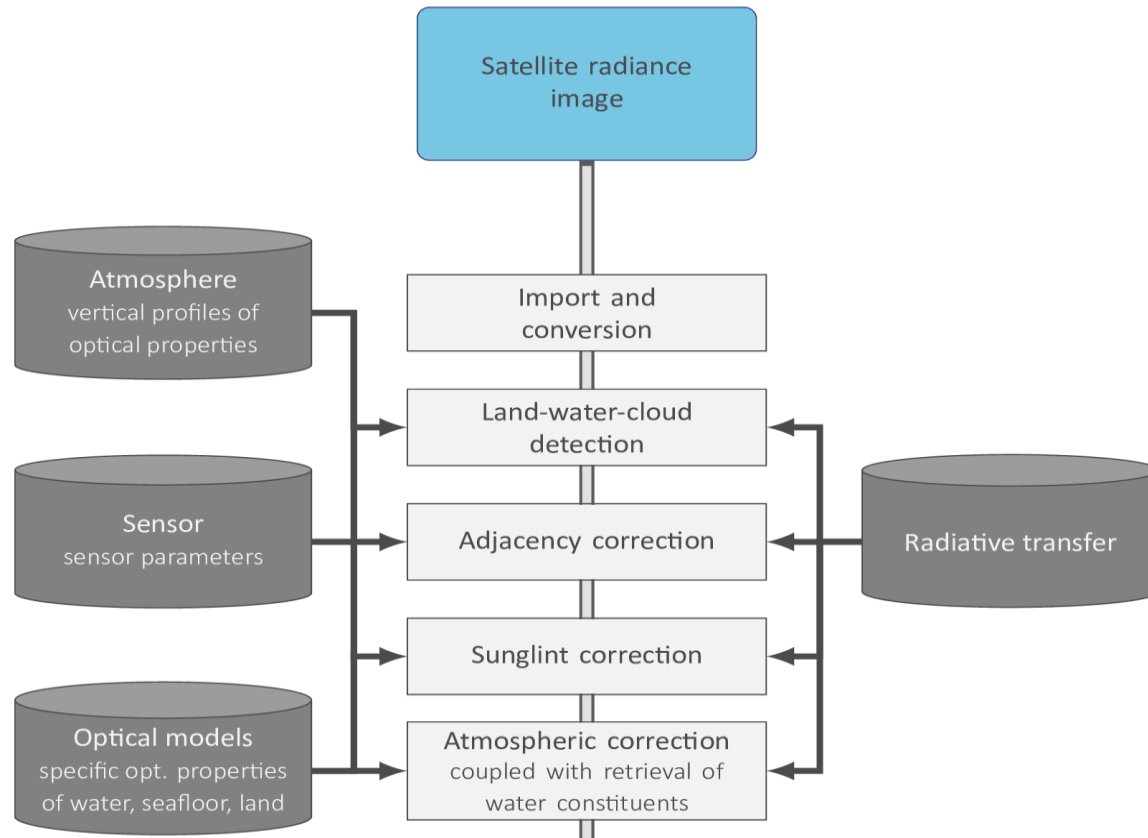


Modular Inversion Processor (MIP)

Fully physics-based processor for EnMAP AC correction over water,
includes coupled AC-water retrieval

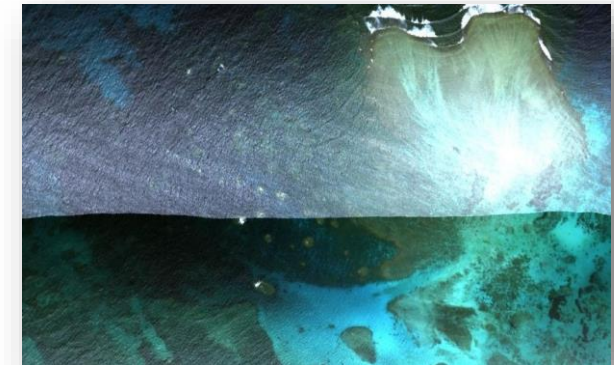
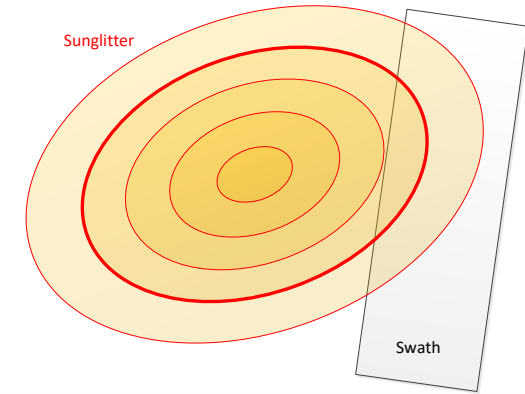


EnMAP Water-related Ground Segment Processors



Modular Inversion Processor (MIP)

Fully physics-based processor for EnMAP AC correction over water, includes coupled AC-water retrieval

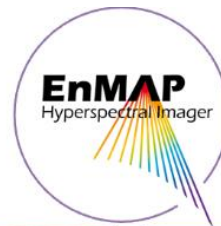
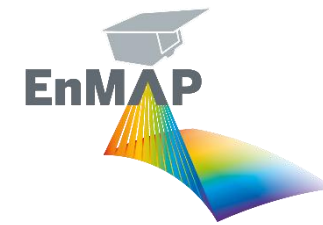


Sunglint avoidance algorithm

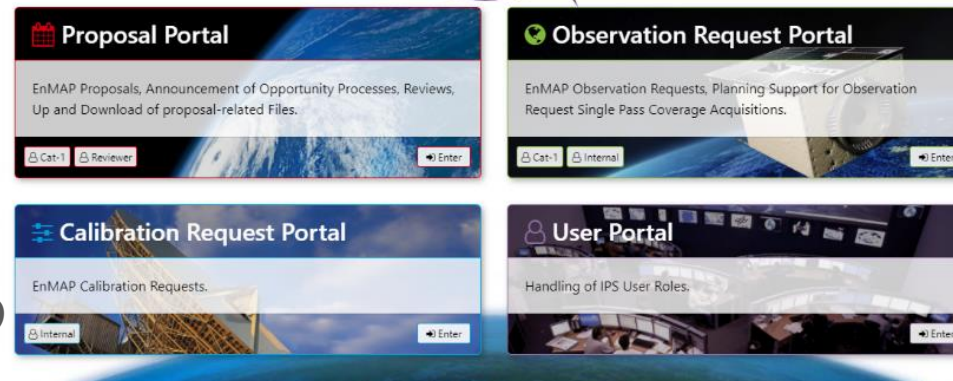
Maximum coverage of areas affected by sunglint will be considered during acquisition planning



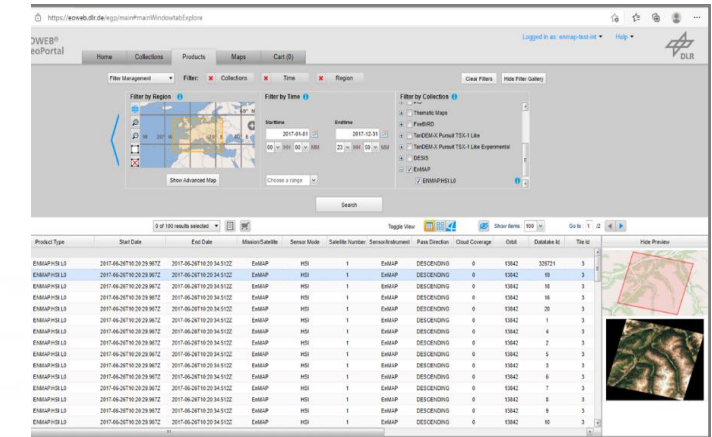
EnMAP Users



- Internal User
 - Mission
 - Charter
- *Category I*
 - *Based on science AO*
 - *With proposal*
- Category II
 - Based on Space Administration
 - Without proposal
- Background Mission

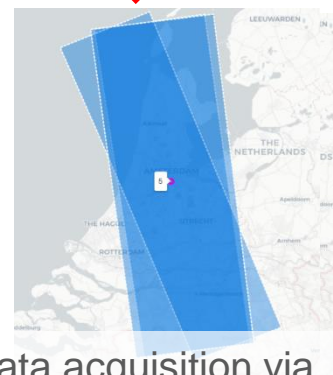


Data access via EOWEB@Geoportal



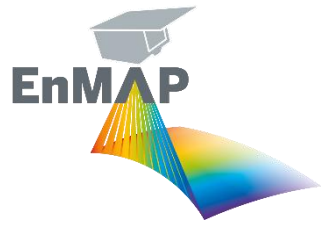
free and open

Year ops	Quota for Category I	Quota for Category II
1	80%	20%
2	70%	30%
3	70%	30%
4	60%	40%
5	60%	40%



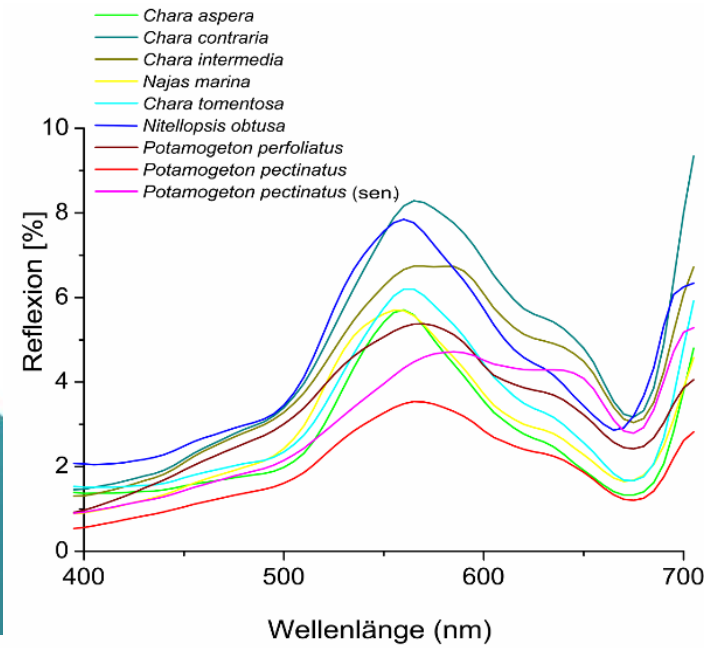
Data acquisition via
EnMAP Instrument Planning Portal

Water Quality Application



Water Quality Application - Submerged Aquatic Vegetation Mapping

Lake Starnberg (Airborne HyMAP Sensor)

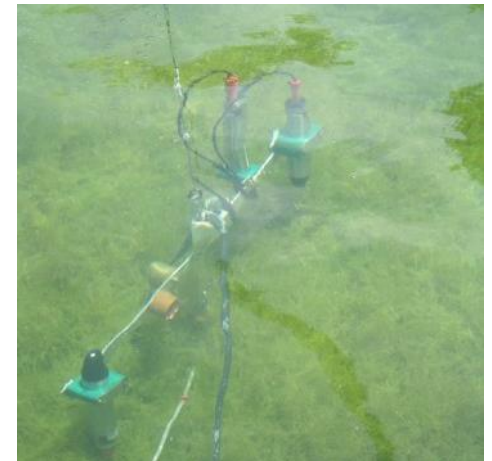
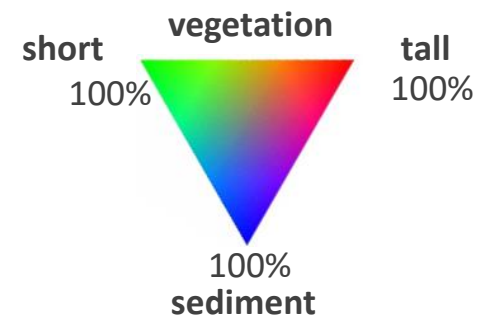


Water Quality Application - Submerged Aquatic Vegetation Mapping

Lake Starnberg (Airborne HyMAP Sensor)

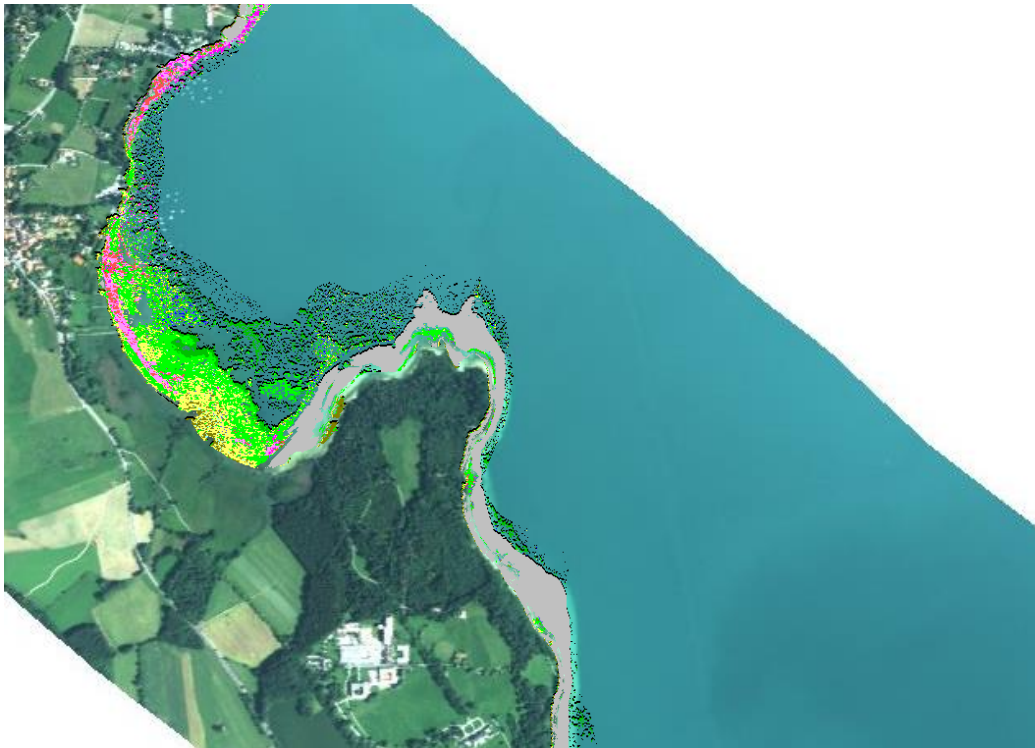


Seafloor coverage [%]












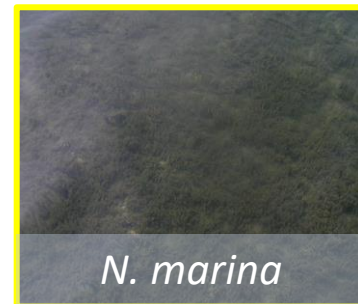
Water Quality Application - Submerged Aquatic Vegetation Mapping

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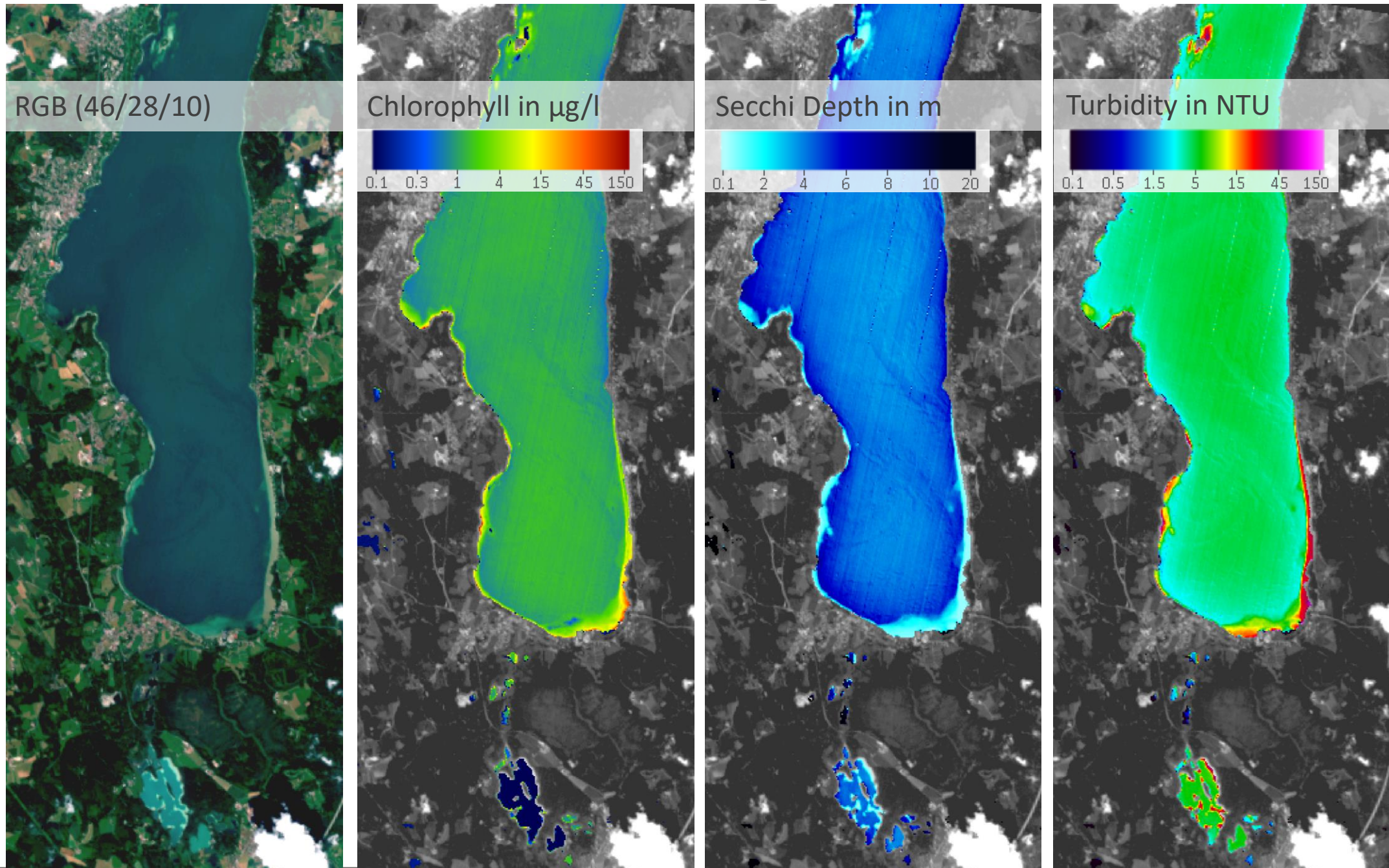
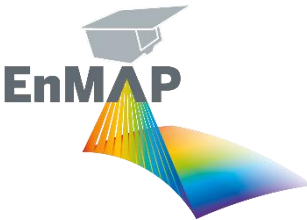


Macrophyte species

-  *P.perfoliatus*
-  *P.pectinatus*
-  *P.pectinatus sen.*
-  *Najas marina*
-  *Chara aspera*
-  *Chara aspera sen.*
-  *Chara contraria*
-  *Chara contraria sen.*
-  uncovered sediment



Water Quality Application – Lake Starnberg, Germany, 24.07.2022



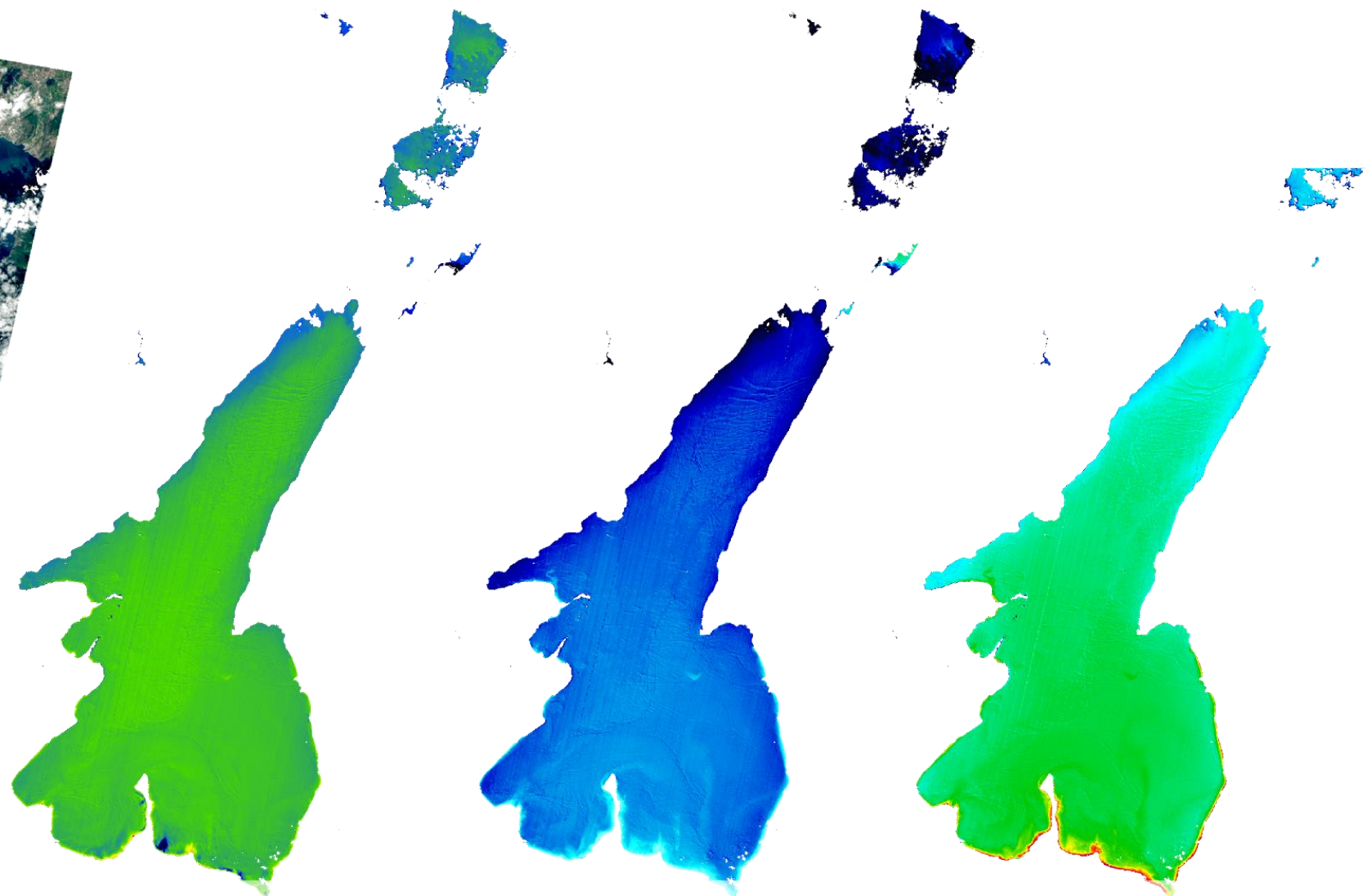
EnMAP Commissioning phase data ©DLR 2022. All rights reserved



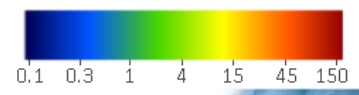
Water Quality Application – Lago di Garda, Italy, 28.07.2022



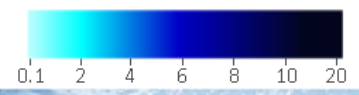
RGB (46/28/10)



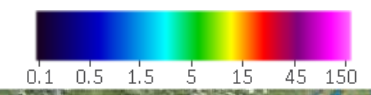
Chlorophyll in $\mu\text{g/l}$

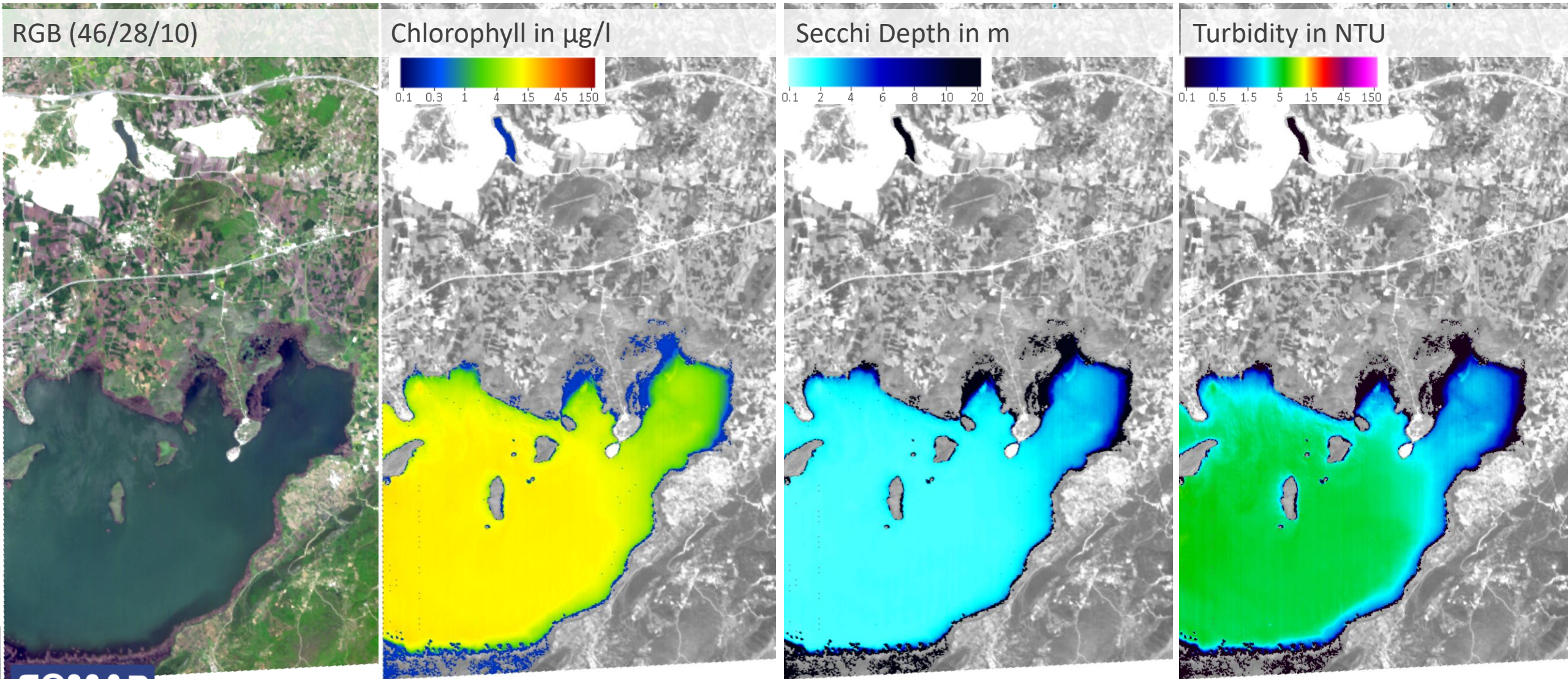
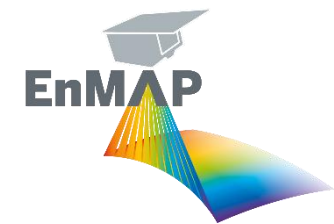


Secchi Depth in m

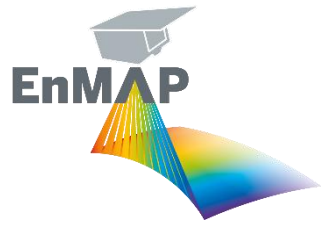


Turbidity in NTU

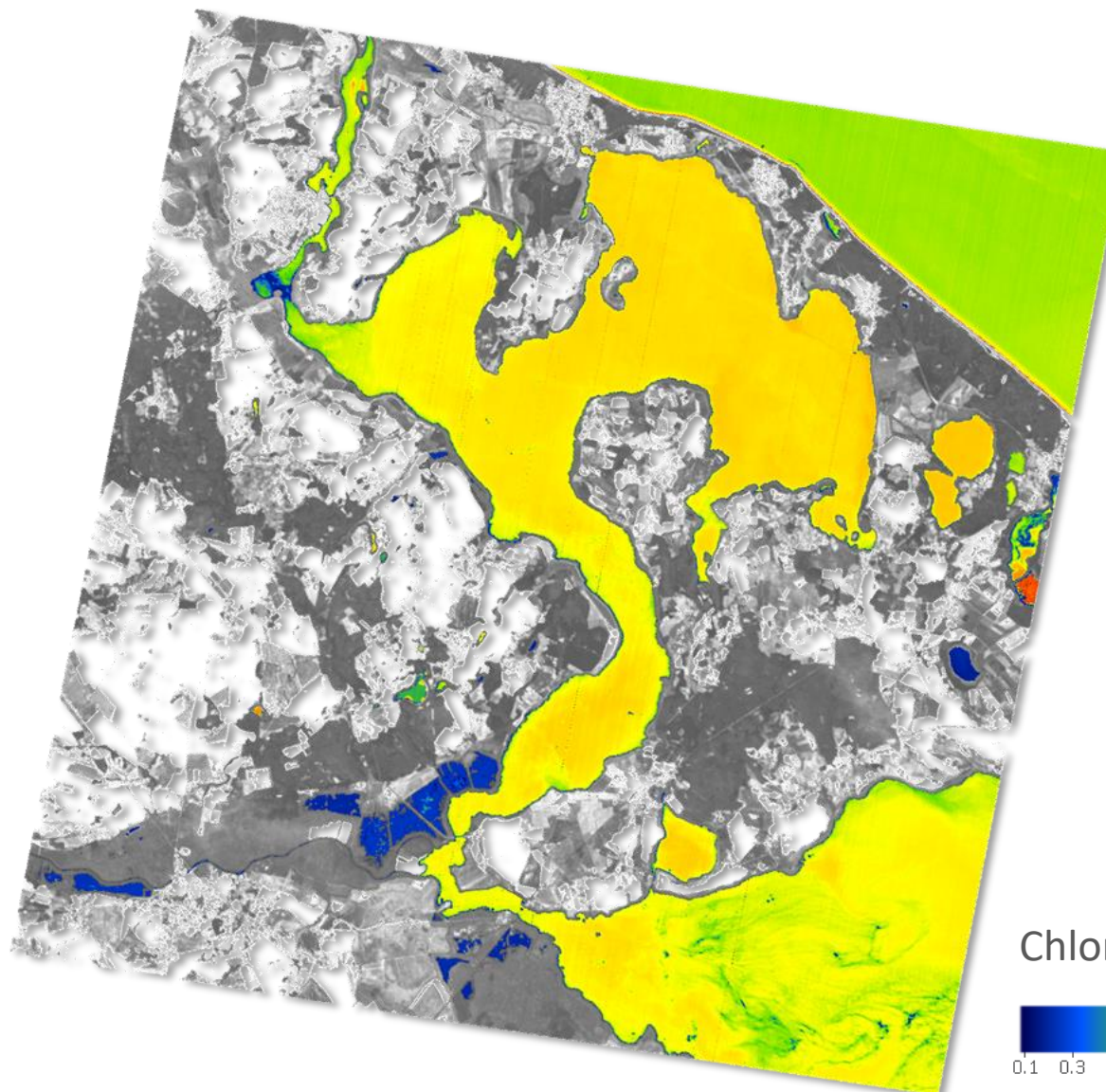
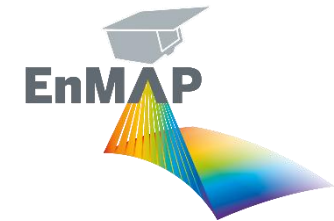




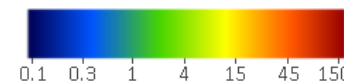
Water Quality Application – Stettiner Haff (Oder), Germany, 24.07.2022

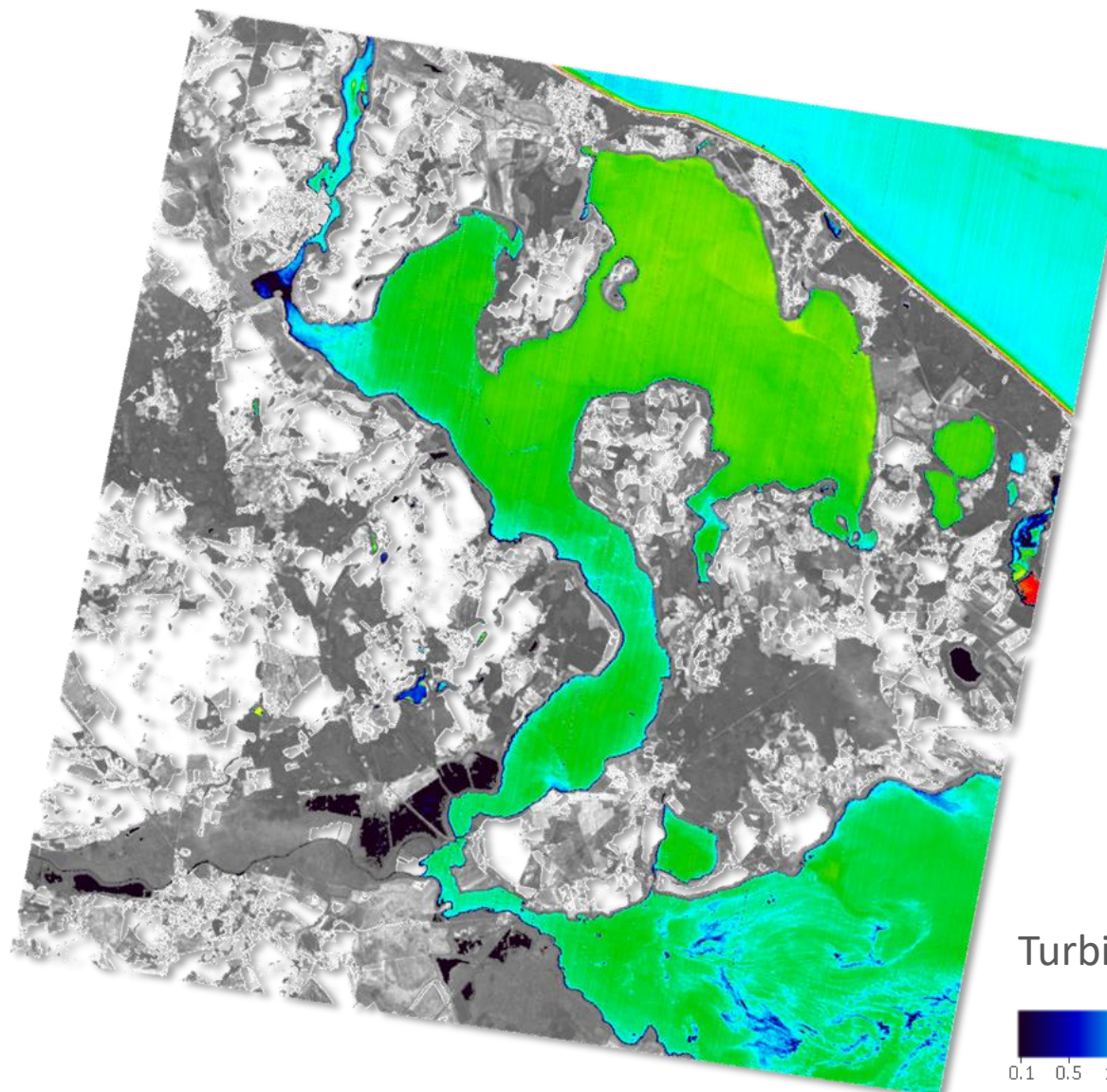
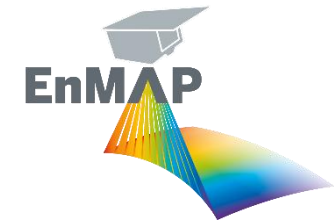


RGB (46/28/10)

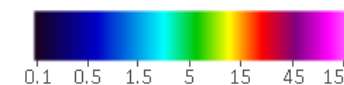


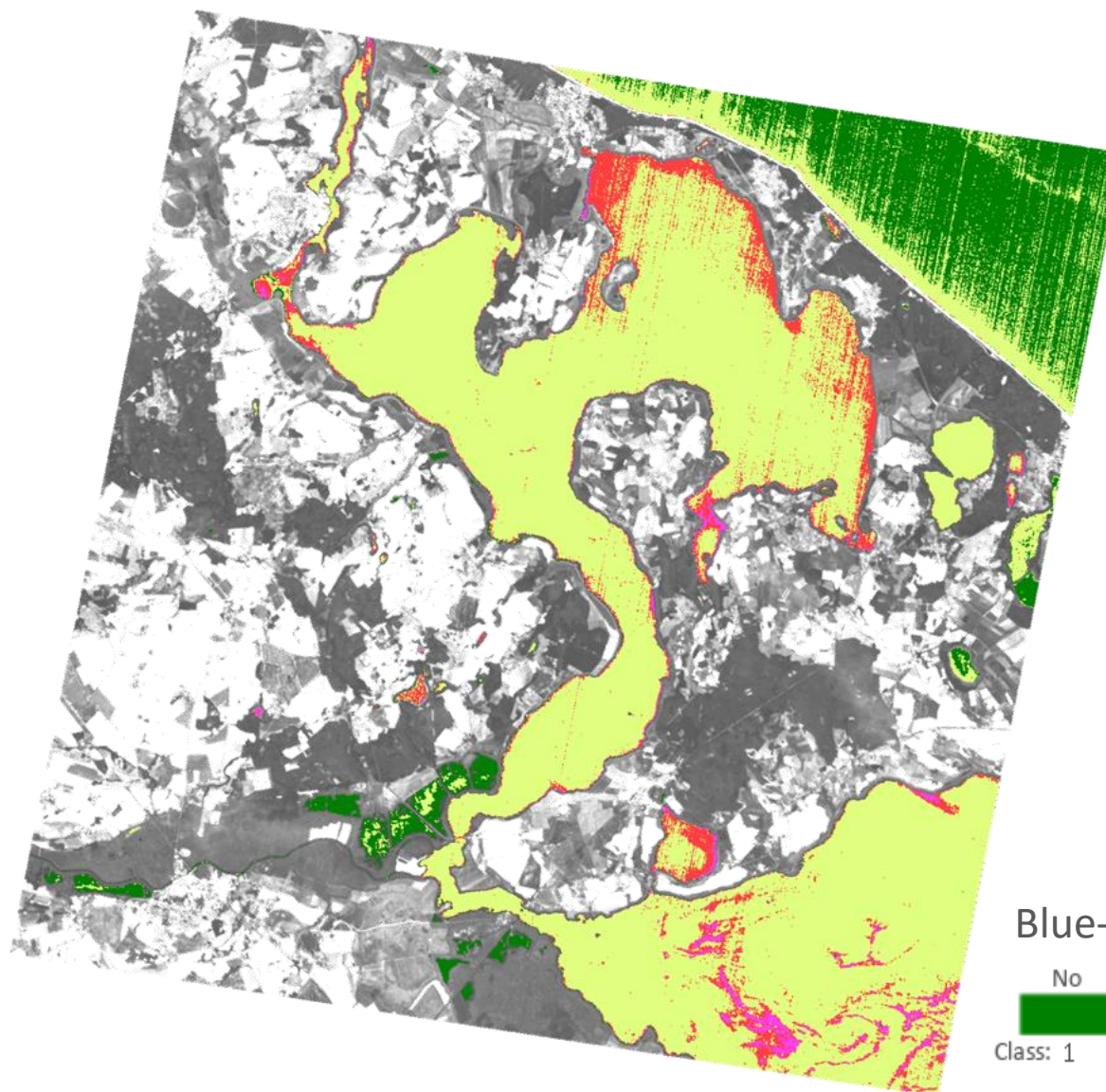
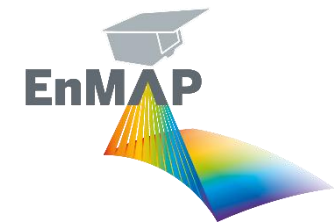
Chlorophyll in µg/l



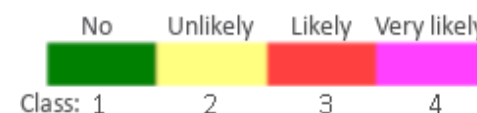


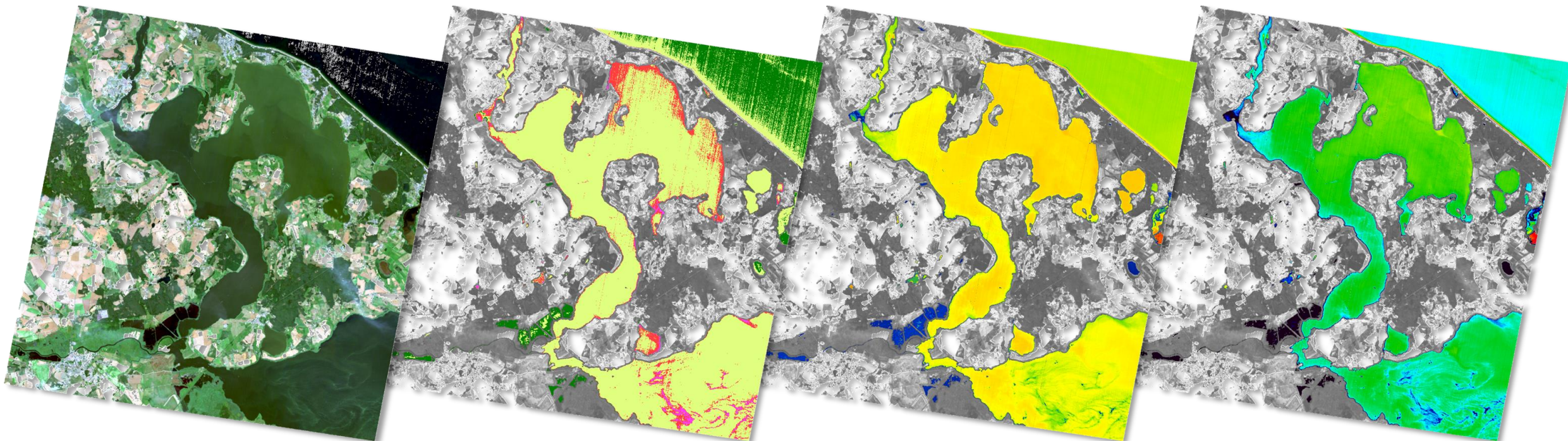
Turbidity in NTU





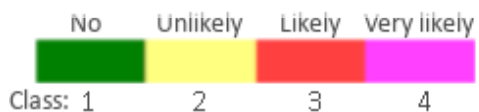
Blue-green Algae Probability



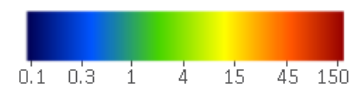


RGB (46/28/10)

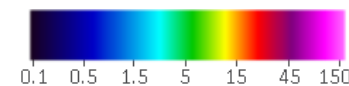
Blue-green Algae Probability



Chlorophyll in $\mu\text{g/l}$



Turbidity in NTU



Outlook

Future operational hyperspectral sensors will in future support space-based services with:

- more detectable species and environmental habitats
- quantitative mapping of major phytoplankton species
- improve legislative mapping (e.g. water frame directive (WRRL))
- improve required assessments in times of climate and environmental changes





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[Brochure \(english\)](#)

[Brochure \(german\)](#)

[Flyer](#)

[Video \(german\)](#) ↗

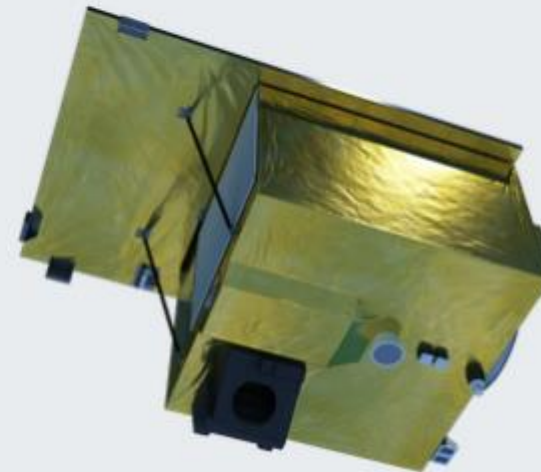
IMAGE GALLERY



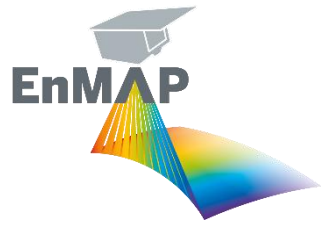
Welcome to EnMAP

The German Spaceborne Imaging Spectrometer Mission

The Environmental Mapping and Analysis Program (EnMAP) is a German hyperspectral satellite mission that aims at monitoring and characterising Earth's environment on a global scale. EnMAP measures and models key dynamic processes of Earth's ecosystems by extracting geochemical, biochemical and biophysical parameters that provide information on the status and evolution of various terrestrial and aquatic ecosystems. For more information about the main objectives and the status have a look at the [mission page](#).



Thank you for your attention!



Contact:

Dr Nicole Pinnel

Email: nicole.pinnel@dlr.de

www.DLR.de

www.enmap.org

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